

Seminar 2021/2022

Sub-Riemannian geometry and its applications

Ivan Beschastnyi, CIDMA, University of Aveiro i.beschastnyi@gmail.com

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In this talk I will explain the basic notions of sub-Riemannian geometry. It is a geometry that models dynamical systems with constraints. Even though its formal definition arose fairly recently, in the end of the XX century, its roots go to antiquity and the isoperimetric problem. After the main definitions are be given, I will show some applications to robotics and neuroscience.